

AMENDMENTS TO THE CLAIMS

This listing of claims replaces all prior versions, and listings, of claims in the application:

Listing of Claims:

Claim 1. (Previously Presented) A channel estimation device comprising: weighting factor generating means for generating weighting factors for weighting and averaging pilot symbols, which are time multiplexed at positions leaning in time to one side in respective slots of a control channel, which is parallel multiplexed with a data channel; and channel estimation value calculating means for weighting and averaging said pilot symbols using said weighting factors and calculating a channel estimation value of data symbols of said data channel,

wherein said weighting factors are determined according to said leaning positions of said pilot symbols in slots of said control channel.

Claim 2. (Original) The channel estimation device as claimed in claim 1, wherein said weighting factor generating means generates weighting factors to be used for weighting and averaging mean values of the pilot symbols in a plurality of slots of said control channel, and said channel estimation value calculating means weights and averages the mean values of said pilot symbols using said weighting factors and calculates the channel estimation value of the data symbols of said data channel.

Claim 3. (Cancelled).

Claim 4. (Previously Presented) A channel estimation device comprising:

weighting factor generating means for generating weighting factors for weighting and averaging pilot symbols, which are time multiplexed with a control channel, which is parallel multiplexed with a data channel; and

channel estimation value calculating means for weighting and averaging said pilot symbols using said weighting factors and calculating a channel estimation value of data symbols of said data channel,

wherein said weighting factor generating means divides data symbols in a slot of said data channel into a plurality of data symbol sections, selects pilot symbols appropriate for calculating the channel estimation value of the data symbols in each of the data symbol sections, and generates the weighting factors which are used for weighting and averaging the pilot symbols and which vary from data symbol section to data symbol section in a slot; and said channel estimation value calculating means takes weighted average of said pilot symbols using said weighting factors and calculates the channel estimation value of the data symbols of each of the data symbol sections.

Claim 5. (Previously Presented) A channel estimation device comprising:

weighting factor generating means for generating weighting factors for weighting and averaging pilot symbols, which are time multiplexed with a control channel, which is parallel multiplexed with a data channel; and

channel estimation value calculating means for weighting and averaging said pilot symbols using said weighting factors and calculating a channel estimation value of data symbols of said data channel,

wherein said weighting factor generating means divides the data symbols in the slots of said data channel into a plurality of data symbol sections, selects the pilot symbols appropriate for calculating the channel estimation value of the data symbols in each of the data symbol sections, and generates the weighting factors to be used for weighting and averaging the pilot symbols; and said channel estimation value calculating means takes weighted average of said pilot symbols using said weighting factors and calculates the channel estimation value of the data symbols of each of the data symbol sections,

wherein in order to calculate the channel estimation value of the data symbols of the last data symbol section of the i -th (i : integer) slot and to calculate the channel estimation value of the data symbols of the first data symbol section of the $(i+1)$ -th slot, said weighting factor generating means selects the same pilot symbol and generates the weighting factors to be used for weighting and averaging the pilot symbols.

Claim 6. (Previously Presented) A channel estimation device comprising:
weighting factor generating means for generating weighting factors for weighting and averaging pilot symbols, which are time multiplexed with a control channel, which is parallel multiplexed with a data channel; and
channel estimation value calculating means for weighting and averaging said pilot symbols using said weighting factors and calculating a channel estimation value of data symbols of said data channel,
wherein the channel estimation device further comprises:
fading frequency decision means for deciding the fading frequency based on an inner product value of said pilot symbols; and
factor altering means for altering the factors that are used in taking said weighted average according to the fading frequency decided by said fading frequency decision means.

Claim 7. (Cancelled).

Claim 8. (Previously Presented) A demodulation device comprising:
weighting factor generating means for generating weighting factors used for weighting and averaging pilot symbols being time multiplexed at positions leaning in time to one side in respective slots of a control channel that was parallel multiplexed together with a data channel;
channel estimation value calculating means for weighting and averaging said pilot symbols using said weighting factors and for calculating a channel estimation value of data symbols of said data channel; and
channel variation compensating means for compensating channel variation of said data symbols using the channel estimation value calculated by said channel estimation value calculating means,
wherein said weighting factors are determined according to said leaning positions of said pilot symbols in slots of said control channel.

Claims 9 – 17. (Cancelled).

Claim 18. (Currently Amended) A channel estimation device for calculating a channel estimation value of data symbols using pilot symbols in a channel in which said data symbols and said pilot symbols are time multiplexed, said channel estimation device comprising:

weighting factor generating means for dividing data symbols in a slot of said channel into a plurality of data symbol sections each of which includes a plurality of data symbols, selecting pilot symbols suitable for calculation of a channel estimation value of data symbols during each data symbol section and generating weighting factors which are to be used for weighting and averaging the pilot symbols and which vary from data symbol section to data symbol section in a slot; and

channel estimation value calculating means for weighting and averaging said pilot symbols using said weighting factors and calculating a channel estimation value of data symbols during each data symbol section.

Claim 19. (Previously Presented) A channel estimation device for calculating a channel estimation value of data symbols using pilot symbols in a channel in which said data symbols and said pilot symbols are time multiplexed, said channel estimation device comprising:

weighting factor generating means for dividing data symbols in a slot of said channel into a plurality of data symbol sections, selecting pilot symbols suitable for calculation of a channel estimation value of data symbols during each data symbol section and generating weighting factors for weighting and averaging said pilot symbols; and

channel estimation value calculating means for weighting and averaging said pilot symbols using said weighting factors and calculating a channel estimation value of data symbols during each data symbol section,

wherein in order to calculate the channel estimation value of the data symbols in the last data symbol section in the i -th (i : integer) slot and to calculate the channel estimation value of the data symbols of the first data symbol section in the $(i+1)$ -th slot, said weighting factor generating means selects the same pilot symbol and generates the weighting factors to be used for weighting and averaging said pilot symbols.

Claim 20. (Previously Presented) The channel estimation device as claimed in claim 18, wherein said weighting factor generating means generates the weighting factors to be used for weighting and averaging mean values of the pilot symbols for each of the plurality of slots of said channel, and said channel estimation value calculating means takes weighted average of the mean values of said pilot symbols using said weighting factors and calculates the channel estimation value of the data symbols in each of the data symbol sections.

Claim 21. (Cancelled).

Claim 22. (Previously Presented) The channel estimation device as claimed in claim 18, further comprising:

fading frequency decision means for deciding the fading frequency based on the inner product value of said pilot symbols; and

factor altering means for altering the factors to be used for taking said weighted averaging according to the fading frequency decided by said fading frequency decision means.

Claim 23. (Previously Presented) A demodulation device comprising:

weighting factor generating means for dividing data symbols in a slot of a channel into which the data symbols and pilot symbols are time multiplexed into a plurality of data symbol sections, selecting pilot symbols appropriate for calculating a channel estimation value of the data symbols in each of the data symbol sections, and generating weighting factors which are to be used for weighting and averaging said pilot symbols and which vary from data symbol section to data symbol section in a slot;

channel estimation value calculating means for weighting and averaging said pilot symbols using said weighting factors and calculating the channel estimation value of the data symbols in each of data symbol sections; and

channel variation compensating means for compensating channel variation of said data symbols using the channel estimation value calculated by said channel estimation value calculating means.

Claims 24 – 32. (Cancelled).

Claim 33. (Previously Presented) A channel estimation device that calculates a channel estimation value of data symbols of a data channel using pilot symbols of a pilot channel which is parallel multiplexed with said data channel, said channel estimation device comprising:

weighting factor generating means for dividing data symbols in said channel into a plurality of data symbol sections each of which includes a plurality of data symbols, selecting for each data symbol section, pilot symbols suitable for calculation of a channel estimation value, and generating for each data symbol section, weighting factors for weighting and averaging said pilot symbols; and

channel estimation value calculating means for weighting and averaging said pilot symbols using said weighting factors and calculating a channel estimation value of data symbols during each data symbol section.

Claim 34. (Original) The channel estimation device as claimed in claim 33, wherein said weighting factor generating means generates the weighting factors to be used for weighting and averaging mean values of the pilot symbols in each of a plurality of sections in said pilot channel, and said channel estimation value calculating means takes weighted average of the mean values of said pilot symbols using said weighting factors and calculates the channel estimation value of the data symbols in each of the data symbol sections.

Claim 35. (Previously Presented) A channel estimation device that calculates a channel estimation value of data symbols of a data channel using pilot symbols of a pilot channel which is parallel multiplexed with said data channel, said channel estimation device comprising:

weighting factor generating means for dividing data symbols in said channel into a plurality of data symbol sections, selecting pilot symbols suitable for calculation of a channel estimation value of data symbols during each data symbol section and generating weighting factors for weighting and averaging said pilot symbols; and

channel estimation value calculating means for weighting and averaging said pilot symbols using said weighting factors and calculating a channel estimation value of data symbols during each data symbol section,

wherein the channel estimation device further comprises:

fading frequency decision means for deciding the fading frequency based on the inner product value of said pilot symbols; and

factor altering means for altering the factors to be used for taking said weighted average according to the fading frequency decided by said fading frequency decision means.

Claim 36. (Currently Amended) A channel estimation method for calculating a channel estimation value of data symbols of a data channel using pilot symbols of a pilot channel that was parallel multiplexed together with said data channel, comprising the steps of:

dividing the data symbols of said data channel into a plurality of data symbol sections each of which includes a plurality of data symbols, selecting pilot symbols appropriate for calculating the channel estimation value of the data symbols in each of the data symbol sections, and generating weighting factors to be used for weighting and averaging the pilot symbols; and

weighting and averaging said pilot symbols using said weighting factors and calculating the channel estimation value of the data symbols in each of the data symbol sections,

wherein a transmission rate of said data channel differs from a transmission rate of said pilot channel.

Claim 37. (Previously Presented) A demodulation device comprising:

weighting factor generating means for dividing data symbols of a data channel into a plurality of data symbol sections each of which includes a plurality of data symbols, selecting for each data symbol section, pilot symbols of a pilot channel that was parallel multiplexed together with said data channel, appropriate for calculating a channel estimation value, and generating for each data symbol section, weighting factors to be used for weighting and averaging the pilot symbols;

channel estimation value calculating means for weighting and averaging said pilot symbols using said weighting factors and calculating the channel estimation value of the data symbols of each of the data symbol sections; and

channel variation compensating means for compensating the channel variation of said data symbols using the channel estimation value calculated by said channel estimation value calculating means.

Claims 38 – 46. (Cancelled).

Claim 47. (Previously Presented) A method for estimating a channel, comprising the steps of:

generating weighting factors to be used for weighting and averaging pilot symbols being time multiplexed at positions leaning in time to one side in respective slots of a control channel that was parallel multiplexed together with a data channel; and

averaging said pilot symbols using said weighting factors and calculating a channel estimation value of data symbols of said data channel,

wherein said weighting factors are determined according to said leaning positions of said pilot symbols in slots of said control channel.

Claim 48. (Cancelled).

Claim 49. (Currently Amended) A channel estimation method for calculating a channel estimation value of data symbols using pilot symbols in a channel in which said data symbols and pilot symbols are time multiplexed, comprising the steps of:

dividing data symbols in a slot of said channel into a plurality of data symbol sections each of which includes a plurality of data symbols, selecting pilot symbols appropriate for acquiring the channel estimation value of the data symbols in each of the data symbol sections, and generating weighting factors which are to be used for weighting and averaging the pilot symbols and which vary from data symbol section to data symbol section in a slot; and

weighting and averaging said pilot symbols using said weighting factors and calculating the channel estimation value of the data symbols in each of the data symbol sections.

Claims 50 – 52. (Cancelled).

Claim 53. (Original) A demodulation device comprising:

channel estimating means for deriving N (N is natural number greater than or equal to two) in number of channel estimation values by weighted averaging of pilot signals in time using N in number of weighted sequences;

compensating means for compensating data sequences using said respective channel estimation values;

RAKE combining means for RAKE combining respective of said N data sequences after compensation; and

reliability judgment means for selecting one data sequence having highest reliability from said N data sequences after RAKE combination.

Claim 54. (Original) A demodulation device comprising:

channel estimating means for deriving N (N is natural number greater than or equal to two) in number of channel estimation values by weighted averaging of pilot signal in time using N in number of weighted sequences for data sequences of predetermined frame number;

compensating means for compensating data sequence using said respective channel estimation values;

RAKE combining means for RAKE combining of said N data sequences after compensation; and

reliability judgment means for selecting N' (N' : natural number, $N' < N$) in number of weighting sequences from said N data sequence after RAKE combining and selecting one data sequence having the highest reliability from N data sequences,

selection of said N' weighting sequences being performed per a predetermined period, for remaining data sequences until performing said reliability judgment again said channel estimation means deriving N' channel estimation value by weighted averaging in time using N' weighting sequences, said compensating means compensating data sequences using N' channel estimation values, said RAKE combining means RAKE combining respective of N' data sequences after compensation, and said reliability judgment means selecting one data sequence having the highest reliability from said N' data sequences.

Claim 55. (Previously Presented) The demodulation device as claimed in claim 53 or 54, wherein said reliability judging means for judging reliability of said data sequence comprises:

error-correction decoding means for performing error-correction decoding of the data sequence after said RAKE combination;

CRC (Cyclic Redundancy Check) bit extracting means for extracting CRC bits added to said data sequence;

CRC decoding means for decoding the CRC for said data sequence;

frame error detecting means for detecting the presence or absence of a frame error based on a decoding result of said CRC;

number-of-frame-error counting means for counting said number of the frame errors in a previously-determined measuring time; and

weight sequence and data selecting means for selecting the weight sequence having high reliability and the data sequence that is demodulated using the weight sequence so selected based on said counting result of the frame errors.

Claim 56. (Previously Presented) The demodulation device as claimed in claim 53 or 54, wherein said reliability judging means for judging reliability of the data sequence comprises:

error-correction decoding means for performing error-correction decoding of the data sequence after said RAKE combination;

likelihood information extracting means for extracting likelihood information that is calculated when performing the error-correction decoding of each of the data sequences;

likelihood averaging means for averaging said extracted likelihood information for a previously-determined measuring time; and

weight sequence and data selecting means for selecting the weight sequence having high reliability and the data sequence that is demodulated using the weight sequence so selected based on said averaged likelihood information.

Claim 57. (Previously Presented) The demodulation device as claimed in claim 53 or 54, wherein said reliability judging means for judging reliability of the data sequence comprises:

electric power calculating means for calculating electric power of each of the data sequences after said RAKE combination;

electric power averaging means for averaging said calculation result of the electric power for a previously-determined measuring time; and

weight sequence and data selecting means for selecting the weight sequence having high reliability and data sequence that is demodulated using the weight sequence so selected based on said averaged electric power.

Claim 58. (Previously Presented) The demodulation device as claimed in claim 53 or 54,

wherein said reliability judging means for judging reliability of the data sequence comprises:

signal-to-noise ratio(ratio of a signal power to a noise power) calculating means for calculating a signal-to-noise ratio of each of the data sequences after said RAKE combination;

signal-to-noise ratio averaging means for averaging the calculation result of said signal-to-noise ratio for a previously-determined measuring time; and

weight sequence and data selecting means for selecting the weight sequence having high reliability and the data sequence that is demodulated using the weight sequence so selected based on said averaged signal-to-noise ratio.

Claim 59. (Previously Presented) The demodulation device as claimed in claim 53 or 54, wherein said reliability judging means for judging reliability of the data sequence comprises:

error-correction decoding means for performing error-correction decoding of the data sequence after said RAKE combination;

CRC bit extracting means for extracting CRC bits added to said data sequence;

CRC decoding means for decoding the CRC for said data sequence;

frame error detecting means for detecting the presence or absence of a frame error based on a decoding result of said CRC;

number-of-frame-error counting means for counting the number of said frame errors in a previously-determined measuring time;

likelihood information extracting means for extracting likelihood information that is calculated when performing error-correction decoding of each of the data sequences;

likelihood averaging means for averaging said extracted likelihood information for a previously-determined measuring time; and

weight sequence and data selecting means for selecting the weight sequence having high reliability and the data sequence that is demodulated using the weight sequence so selected based on said counted number of frame errors of the plurality of data sequences and said averaged likelihood information.

Claim 60. (Previously Presented) The demodulation device as claimed in claim 53 or 54, wherein said reliability judging means for judging reliability of the data sequence comprises:

error-correction decoding means for performing error-correction decoding of the data sequence after said RAKE combination;

CRC bit extracting means for extracting CRC bits added to said data sequence;

CRC decoding means for decoding the CRC for said data sequence;

frame error detecting means for detecting the presence or absence of a frame error based on a decoding result of said CRC;

number-of-frame-error counting means for counting said number of the frame errors in a previously-determined measuring time;

electric power calculating means for calculating electric power of each of the data sequences after said RAKE combination;

electric power averaging means for averaging said calculation result of the electric power for a previously-determined measuring time; and

weight sequence and data selecting means for selecting the weight sequence having high reliability and the data sequence that is demodulated using the weight sequence so selected based on said number of frame errors and said averaged electric power.

Claim 61. (Previously Presented) The demodulation device as claimed in claim 53 or 54, wherein said reliability judging means for judging reliability of the data sequence comprises:

error-correction decoding means for performing error-correction decoding of the data sequence after said RAKE combination;

CRC bit extracting means for extracting CRC bits added to said data sequence;

CRC decoding means for decoding the CRC for said data sequence;

frame error detecting means for detecting the presence or absence of a frame error based on a decoding result of said CRC;

number-of-frame-error counting means for counting said number of the frame errors in a previously-determined measuring time;

signal-to-noise ratio calculating means for calculating a signal-to-noise ratio (ratio of a signal power to a noise power) of each of the data sequences after said RAKE combination;

signal-to-noise ratio averaging means for averaging the calculation result of said signal-to-noise ratio for a previously-determined measuring time; and

weight sequence and data selecting means for selecting weight sequence having high reliability and the data sequence that is demodulated using the weight sequence so selected based on said number of frame errors and said averaged signal-to-noise ratio.

Claim 62. (Previously Presented) A demodulation device receiving a pilot signal and a data sequence that are multiplexed in a channel and demodulating the data sequence using the pilot signal, the demodulation device comprising:

channel estimating means for weighted averaging of the pilot signal using a plurality of predetermined weighting sequences and for deriving a plurality of channel estimation values;

demodulating means to which the data sequence is input, the demodulating means performing phase correction by applying the plurality of channel estimation values to the data sequence, thereby generating and outputting a plurality of demodulated data sequences; and

reliability judging means for calculating a reliability for each of said plurality of demodulated data sequences and for selecting one of the plurality of demodulated data sequences based on the reliabilities of said plurality of demodulated data sequences, the reliability judging means outputting the selected one of the plurality of demodulated data sequences.

Claim 63. (Original) The demodulation device as claimed in claim 62, wherein said reliability judging means comprises selecting means for selecting predetermined number of the weight sequences from among said plurality of weight sequences based on a judgment result of reliability of said plurality of demodulated data sequences, and

said demodulating means performs the demodulation using only said predetermined number of the weight sequences, when said predetermined number of the weight sequences were selected.

Claim 64. (Previously Presented) The demodulation device as claimed in any one of claims 53, 54 or 62, wherein said pilot signals are time multiplexed in a control channel that was parallel multiplexed together with a data channel in which said data sequence is contained.

Claim 65. (Previously Presented) The demodulation device as claimed in any one of claims 53, 54 or 62, wherein said pilot signals are time multiplexed in one channel together with said data sequence.

Claim 66. (Original) The demodulation device as described in claim 65, wherein said channel estimating means divides the data sequence in the slots of said channel into a plurality of data sequence sections, selects pilot signals appropriate for calculating the channel estimation value of the data in each of the data sequence sections, and calculates the channel estimation value of the data of each of the data sequence sections by weighting and averaging the selected pilot signals.

Claim 67. (Previously Presented) The demodulation device as claimed in any one of claims 53, 54 or 62, wherein said pilot signals are contained in a pilot channel that was parallel multiplexed together with the data channel containing said data sequence.

Claim 68. (Original) The demodulation device as claimed in claim 67, wherein said channel estimating means divides said data sequence into a plurality of data sequence sections, selects pilot signals appropriate for calculating the channel estimation value of the data in each of the data sequence sections, and calculates the channel estimation value of the data in each of the data sequence sections by weighting and averaging the selected pilot signals.

Claim 69. (Previously Presented) A demodulation method comprising:
the step of obtaining N pieces of channel estimation values by time-weighting and averaging pilot signals using N (N: natural number greater than or equal to 2) sets of weight sequences;
the step of compensating data sequence using each of said channel estimation values;
the step of RAKE combining each of the N sets of the data sequences after said compensation; and
the reliability judgment step of selecting one set of the data sequences having the highest reliability from among the N sets of the data sequences after said RAKE combination.

Claim 70. (Original) A demodulation method comprising:

the step of obtaining N (N: natural number greater than or equal to 2) pieces of channel estimation values by time-weighting and averaging pilot signals using N sets of weight sequences with respect to a previously-determined number of frames of data sequence;

the step of compensating the data sequence using each of said channel estimation values;

the step of RAKE combining each of N sets of the data sequences after said compensation; and

the reliability judgment step of selecting N' (N': natural number; $N' < N$) sets of the weight sequences having high reliability from among said N sets of the data sequences after said RAKE combination and selecting one set of data sequence having the highest reliability from among the N sets of the data sequences after said RAKE combination,

wherein the selection of said N' sets of the weight sequences is conducted at regular intervals, and throughout a period up to a time when said judgment of reliability is made next time, with respect to remaining part of the data sequence, in said step of estimating the channel, N' pieces of the channel estimation values are obtained by time-weighting and averaging the data sequence using the N' sets of the weight sequences; in said step of compensating, the data sequence is compensated using the N' pieces of the channel estimation values; in said step of the RAKE combination, each of the N' sets of the data sequences after the compensation is RAKE combined; and in said reliability judgment step, one set of the data sequence having the highest reliability is selected from among the N' sets of the data sequences.

Claim 71. (Original) The demodulation method as claimed in claim 69 or 70, wherein said reliability judgment step comprises the steps of:

- error-correction decoding the data sequence after said RAKE combination;
- extracting CRC bits added to said data sequence;
- decoding the CRC with respect to said data sequence;
- detecting the presence or absence of a frame error based on said demodulation result of the CRC;
- counting the number of said frame errors in a previously-determined measuring time; and
- selecting the weight sequence having high reliability and the data sequence that is demodulated using the weight sequence so selected based on said counting result of the frame errors.

Claim 72. (Original) The demodulation method as claimed in claim 69 or 70, wherein said reliability judgment step comprises the steps of:

- error-correction decoding the data sequence after said RAKE combination;
- extracting likelihood information calculated when performing error-correction decoding of each of the data sequence;
- averaging said extracted likelihood information for a previously-determined measuring time; and
- selecting the weight sequence having high reliability and the data sequence that is demodulated using the weight sequence so selected based on said averaged likelihood information.

Claim 73. (Original) The demodulation method as claimed in claim 69 or 70, wherein said reliability judgment step comprises the steps of:

- calculating electric power of each of the data sequences after said RAKE combination;
- averaging the calculation result of said electric power for a previously-determined measuring time; and
- selecting the weight sequence having high reliability and the data sequence that is demodulated using the weight sequence so selected based on said averaged electric power.

Claim 74. (Original) The demodulation method as claimed in claim 69 or 70, wherein said reliability judgment step comprises the steps of:

calculating a signal-to-noise ratio of each of the data sequences after said RAKE combination;

averaging the calculation result of said signal-to-noise ratios for a previously-determined measuring time; and

selecting the weight sequence having high reliability and the data sequence that is demodulated using the weight sequence so selected based on said averaged signal-to-noise ratio.

Claim 75. (Original) The demodulation method as claimed in claim 69 or 70, wherein said reliability judgment step comprises the steps of:

performing error-correction decoding of the data sequences after said RAKE combination;

extracting CRC bits added to said data sequence;

decoding the CRC with respect to said data sequence;

detecting the presence or absence of a frame error based on said decoding result of the CRC;

counting said number of the frame errors in a previously-determined measuring time;

extracting likelihood information that is calculated when performing error-correction decoding of each of the data sequences;

averaging said extracted likelihood information for a previously-determined measuring time; and

selecting the weight sequence having high reliability and the data sequence that is demodulated using the weight sequence so selected based on said measured number of the frame errors of the plurality of the data sequences and said averaged likelihood information.

Claim 76. (Original) The demodulation method as claimed in either of claim 69 or 70, wherein said reliability judgment step comprises the steps of:

- error-correction decoding said data sequences after said RAKE combination;
- extracting CRC bits added to said data sequence;
- decoding the CRC with respect to said data sequence;
- detecting the presence or absence of a frame error based on the decoding result of said CRC;
- counting the number of said frame errors in a previously-determined measuring time;
- calculating electric power of each of received data sequences after said RAKE combination;
- averaging the calculation result of said electric power for a previously-determined measuring time; and
- selecting the weight sequence having high reliability and the data sequence that is demodulated using the weight sequence so selected based on said number of frame errors and said averaged electric power.

Claim 77. (Original) The demodulation method of as claimed in claim 69 or 70, wherein said reliability judgment step comprises the steps of:

- error-correction decoding said data sequences after said RAKE combination;
- extracting CRC bits added to said data sequence;
- decoding the CRC with respect to said data sequence;
- detecting the presence or absence of a frame error based on the decoding result of said CRC;
- counting the number of said frame errors in a previously-determined measuring time;
- calculating a signal-to-noise ratio of each of the data sequences after said RAKE combination;
- averaging calculation result of said signal-to-noise ratios for a previously-determined measuring time; and
- selecting the weight sequence having a high reliability and the data sequence that is demodulated with the weight sequence so selected based on the number of said frame errors and said averaged signal-to-noise ratio.

Claim 78. (Previously Presented) A demodulation method used in a demodulation device which receives a pilot signal and a data sequence that are multiplexed in a channel and demodulates the data sequence using the pilot signal, comprising the steps of:

weighting and averaging the pilot signal using a plurality of predetermined weight sequences to obtain a plurality of channel estimation values;

deriving a plurality of demodulated data sequences from the data sequence by performing phase correction in which said plurality of channel estimation values are applied to the data sequence;

calculating a reliability for each of said plurality of demodulated data sequences;

selecting one of the plurality of demodulated data sequences based on the reliability of each of said plurality of demodulated data sequences; and

outputting the selected demodulated data sequence.

Claim 79. (Original) The demodulation method as claimed in claim 78, wherein, based on the judgment result of reliability of said plurality of demodulated data sequences, a predetermined number of weight sequences are selected from among said plurality of weight sequences, and after the selection, demodulation through the use of only the selected weight sequences is performed.

Claim 80. (Previously Presented) The demodulation method as claimed in any one of claims 69, 70 or 78, wherein said pilot signals are time multiplexed into a control channel that is parallel multiplexed together with a data channel in which said data sequence is contained.

Claim 81. (Previously Presented) The demodulation method as claimed in any one of claims 69, 70 or 78, wherein said pilot signals are time multiplexed into one channel together with said data sequence.

Claim 82. (Original) The demodulation method as claimed in claim 81, wherein said step of estimating a channel divides said data sequence in the slots of said channel into a plurality of data sequence sections, selects pilot signals appropriate for calculating the channel estimation value of the data of each of the data sequence sections, and calculates a channel estimation value of the data of each of the data sequence sections by weighting and averaging the selected pilot signals.

Claim 83. (Previously Presented) The demodulation method as claimed in any one of claims 69, 70 or 78, wherein said pilot signals are contained in a pilot channel that was parallel multiplexed together with a data channel containing said data sequence.

Claim 84. (Original) The demodulation method as claimed in claim 83, wherein said step of estimating a channel divides said data sequence into a plurality of data sequence sections, selects pilot signals appropriate for calculating the channel estimation value of the data in each of the data sequence sections, and calculates the channel estimation value of the data of each of the data sequence sections by weighting and averaging the selected pilot signals.

Claim 85. (Previously Presented) A channel estimation device for calculating a channel estimation value of data symbols using pilot symbols in a channel in which said data symbols and said pilot symbols are time multiplexed, said channel estimation device comprising:

weighting factor generating means for dividing data symbols in a slot of said channel into a plurality of data symbol sections, selecting pilot symbols suitable for calculation of a channel estimation value of data symbols during each data symbol section and generating weighting factors for weighting and averaging said pilot symbols; and

channel estimation value calculating means for weighting and averaging said pilot symbols using said weighting factors and calculating a channel estimation value of data symbols during each data symbol section,

wherein said pilot symbols are time multiplexed at positions leaning in time to one side in respective slots of said channel, and

said weighting factors are determined according to said leaning positions of said pilot symbols in slots of said channel.